

**Amendments to the Specification:**

Please replace paragraph [0043] with the following new paragraph:

[0043] For example, in the aforementioned embodiment, the taper surfaces 18b are formed on axially both sides of the cylindrical surface 18a of the outer roller 18, and the taper lateral surfaces 24b and 24c are formed in the lateral surface of the guide groove 24 at the portions opposed to the taper surfaces 18b. However, the invention is not limited to the embodiment. For example, as a first modified example, a chamfer 40 that is a curved surface may be formed on each of axially both sides of the cylindrical surface 18a' of the outer roller 18', as a substitute of part of the taper surface 18b', as shown in FIG. 7. Also, as a second modified example, a chamfer that is a curved surface 40 may be formed on each of axially both sides of the cylindrical surface 18a'' of the outer roller 18'' as a substitute of part of the taper surface 18b'', and a concave curved surface 42 may be formed on each of both sides of the flat lateral surface 24a of the guide groove 24, as a substitute of each of part of the taper surfaces 24b and 24c, or as a substitute of each of the entire taper surfaces 24b and 24c, as shown in FIG. 8. Also, as a third modified example, a convex curved surface 44 that protrudes toward the inner side of the outer joint member 12 may be formed, as shown in FIG. 9. In the first modified example (FIG. 7), the second modified example (FIG. 8), and the third modified example (FIG. 9), it is possible to more reliably prevent the end surface of the outer roller 18''' on the axially outer side from making contact with the inner surface of the outer joint member 12, as in the aforementioned embodiment. Also, it is easy to manufacture the constant velocity universal joint in which chamfers 40 and 42 are formed on axially both sides of the cylindrical surface 18a'' of the outer roller 18'', and on both sides of the flat lateral surface 24a of the guide groove 24 as in the second modified example (FIG. 8), as compared to the constant velocity universal joint in the aforementioned embodiment, the first modified example (FIG. 7), and the third modified example (FIG. 9).

Please replace paragraph [0044] with the following amended paragraph:

[0044] Also, in the aforementioned embodiment, three leg shafts 30 are provided; however, other arrangements are possible. ~~However, four or more leg shafts may be provided.~~